

Numerical Study of Navier-Stokes Equations in Supersonic Flow over a Double Wedge Airfoil using Adaptive Grids

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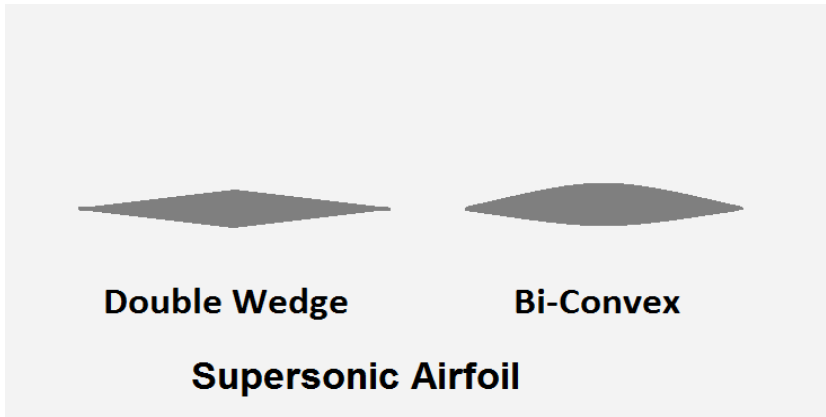
Excerpt from the Proceedings of the 2012 COMSOL Conference in Bangalore

Supersonic Flight



Shock wave formed on supersonic flight (Courtesy:Ensign John Gay, US Navy)

Supersonic Airfoils



Supersonic Airfoil

- Thinner cross-section
- Sharper leading and trailing edge

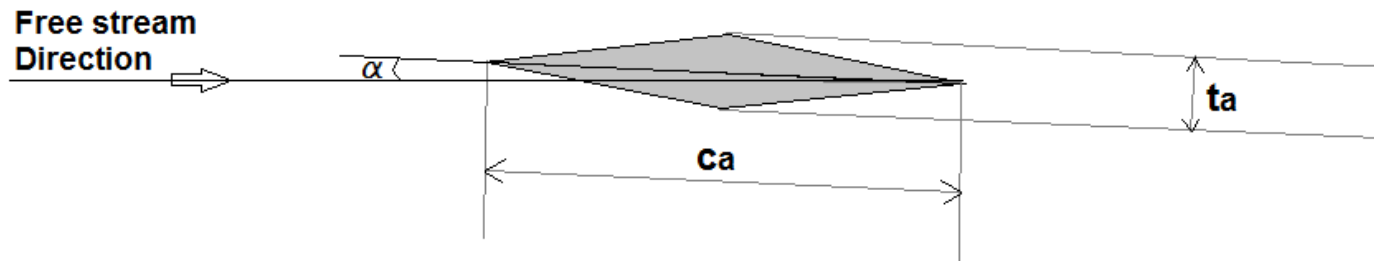
Subsonic Airfoil

- Thicker cross-section
- Rounded leading and trailing edge



Subsonic Airfoil

Symmetrical Double Wedge Airfoil



$$t_c = \frac{t_a}{c_a} : \{0.08, 0.1 \text{ and } 0.12\}$$

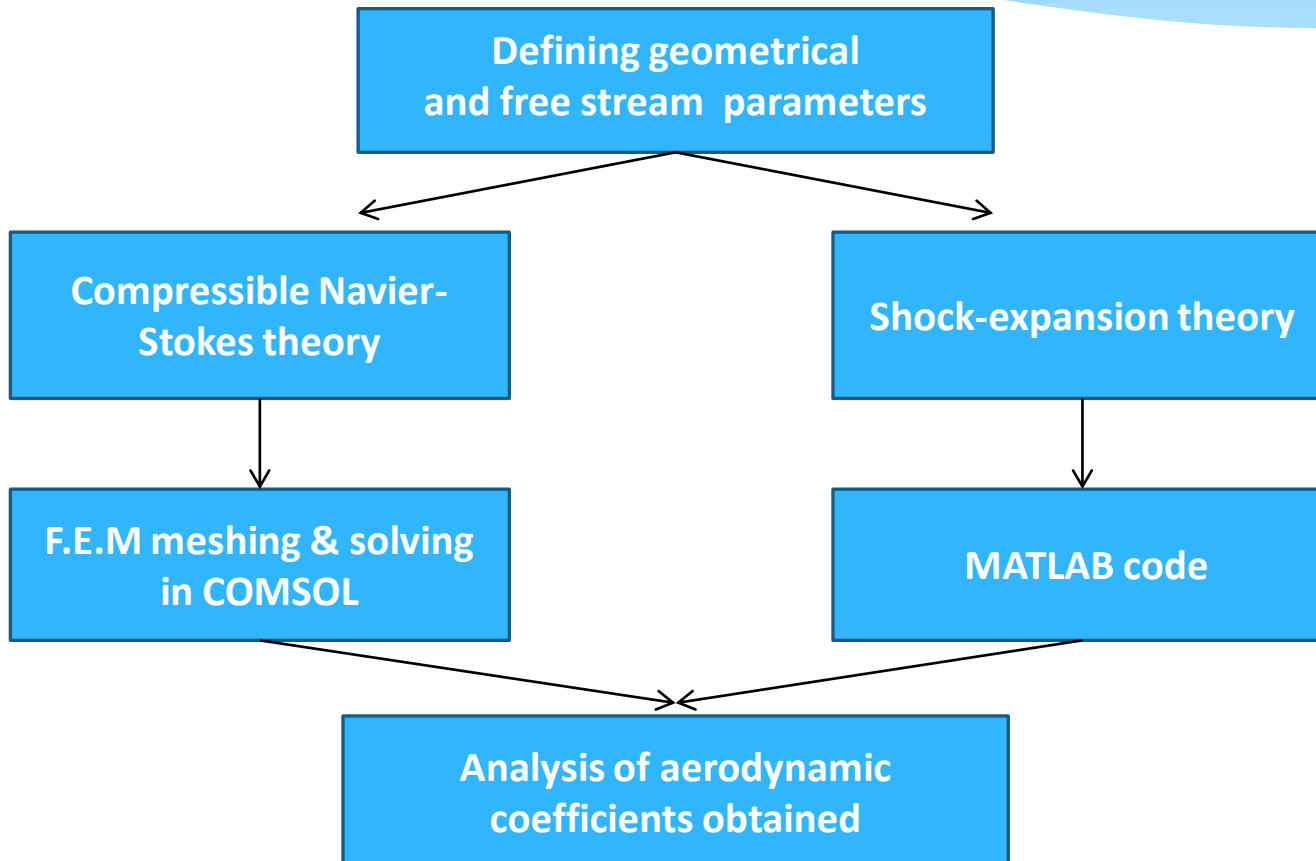
$$\alpha : \{0^{\circ}, 1^{\circ}, 2^{\circ}, 3^{\circ}, 4^{\circ}, 5^{\circ}, 8^{\circ} \text{ and } 12^{\circ}\}$$

- c_a : Chord Length
- t_a : Thickness
- α : Angle of attack

Aerodynamic Coefficients

- Section aerodynamic coefficients of an airfoil is defined below:
 - Coefficient of pressure $C_p = \frac{p-p_\infty}{\frac{1}{2}\rho_\infty \cdot V_\infty^2}$
 - Coefficient of Lift $C_L = \frac{L}{\frac{1}{2}\rho_\infty \cdot V_\infty^2 \cdot c}$
 - Coefficient of Drag $C_D = \frac{D}{\frac{1}{2}\rho_\infty \cdot V_\infty^2 \cdot c}$

Evaluation of Aerodynamic coefficients



Compressible Navier-Stokes Theory

Non-conservative form:

Mass Conservation:
$$\frac{\partial \rho}{\partial t} + \rho \cdot \nabla \cdot (\mathbf{u}) + (\mathbf{u} \cdot \nabla) \rho = 0$$

Momentum Conservation:
$$\rho \left(\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} \right) = \nabla \cdot \left[-p \cdot \mathbf{I} + \mu \cdot \left((\nabla \mathbf{u}) + (\nabla \mathbf{u})^T - \frac{2}{3} \cdot \nabla \cdot \mathbf{u} \cdot \mathbf{I} \right) \right]$$

Temperature equation:
$$\begin{aligned} \rho \cdot C_p \left(\frac{\partial T}{\partial t} + (\mathbf{u} \cdot \nabla) T \right) = & \nabla \cdot (k \cdot \nabla T) + \frac{T}{\rho} \cdot \left(\frac{\partial \rho}{\partial T} \right)_p \left(\frac{\partial p}{\partial t} + (\mathbf{u} \cdot \nabla) p \right) \\ & + \nabla \mathbf{u} : \left[\mu \cdot \left((\nabla \mathbf{u}) + (\nabla \mathbf{u})^T - \frac{2}{3} \cdot \nabla \cdot \mathbf{u} \cdot \mathbf{I} \right) \right] \end{aligned}$$

Ideal gas formulation:
$$p = \rho \cdot R \cdot T$$

Numerical Simulation

- Boundary and Initial conditions:

| Free stream parameters | Domain inlet values |
|-----------------------------|---------------------|
| Mach numbers (M_∞) | 2.5 |
| Temperature (T_∞) | 218 K |
| Pressure (P_∞) | 0.2 atm |

Domain outlet condition:

$$\nabla T \cdot \mathbf{n} = 0$$

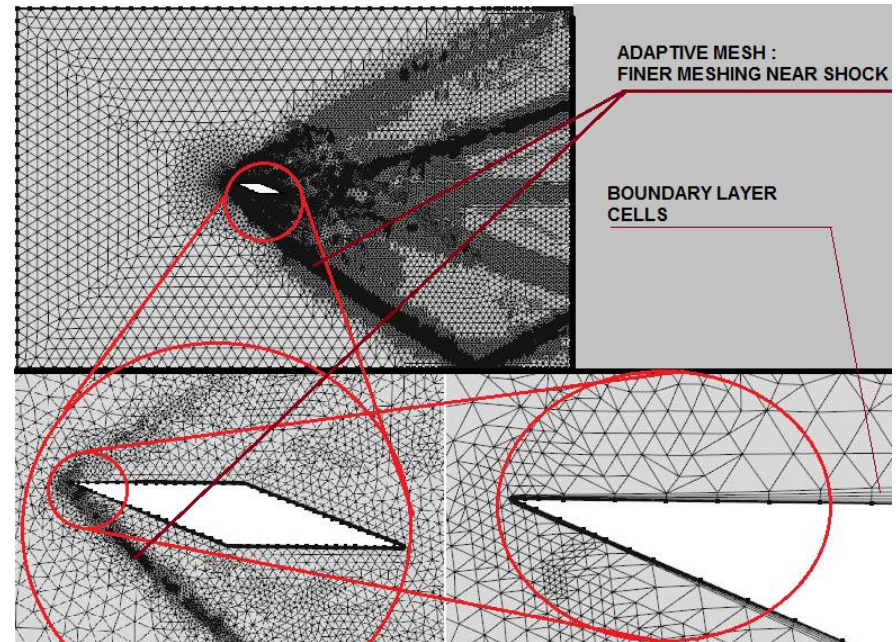
| Initial domain parameters | Initial domain values for Euler computation |
|---------------------------|---|
| Pressure(p) | 0.2 atm |
| Mach Number(M) | 2.5 |
| Temperature(T) | 218 K |

Grid generation

- Two level adaptive meshing feature on unstructured triangular mesh with first order element is implemented.
- Boundary-Layer cells are added to grid obtained from adaptive meshing.

Solver

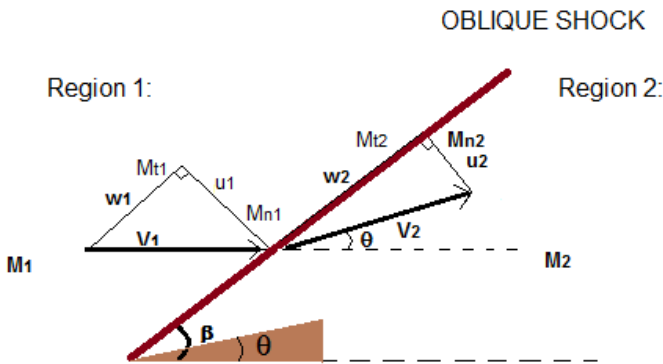
- Viscous computation is initialised with prior solution obtained from Euler equations
- All the primary variables while are fully coupled and are solved using pseudo time stepping with a stationary solver.
- The convergence was determined by setting the relative tolerance to 0.01.



Adaptive mesh with boundary layer cells for Adaptive grid for $t_c = 0.1$ and $\alpha = 12^\circ$ case.

Shock-Expansion Theory

Oblique Shock



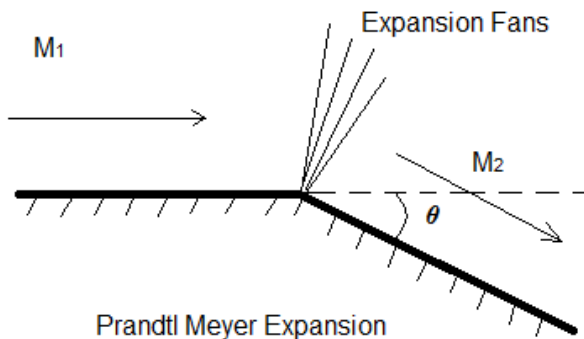
$\beta - \theta - M$ Relation

$$\tan(\beta) = \frac{\left(M_1^2 - 1 + 2 \cdot \lambda \cdot \cos \left[\left(4 \cdot \pi \cdot \delta + \frac{\cos^{-1}(\chi)}{3} \right) \right] \right)}{3 \cdot \left(1 + \frac{(\gamma - 1)}{2} \cdot M_1^2 \right) \cdot \tan(\theta)}$$

$$\lambda = \left[(M_1^2 - 1)^2 - 3 \cdot \left(1 + \frac{(\gamma - 1)}{2} \cdot M_1^2 \right) \cdot \left(1 + \frac{(\gamma + 1)}{2} \cdot M_1^2 \right) \cdot \tan^2(\theta) \right]^{\frac{1}{2}}$$

$$\chi = \frac{\left((M_1^2 - 1)^3 - 9 \cdot \left(1 + \frac{(\gamma - 1)}{2} \cdot M_1^2 \right) \cdot \left(1 + \frac{(\gamma - 1)}{2} \cdot M_1^2 + \frac{(\gamma + 1)}{4} \cdot M_1^4 \right) \cdot \tan^2(\theta) \right)}{\lambda^3}$$

Prandtl-Meyer Expansion



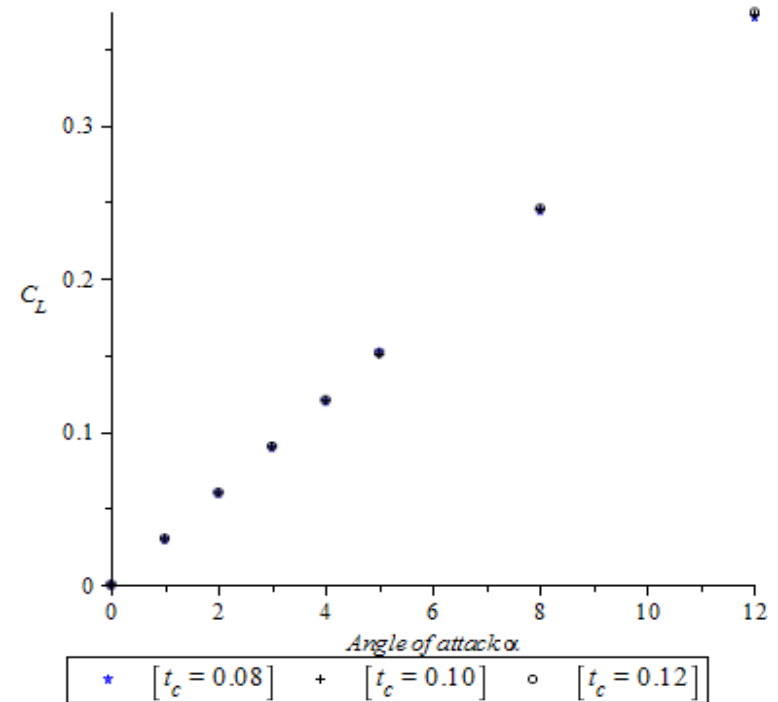
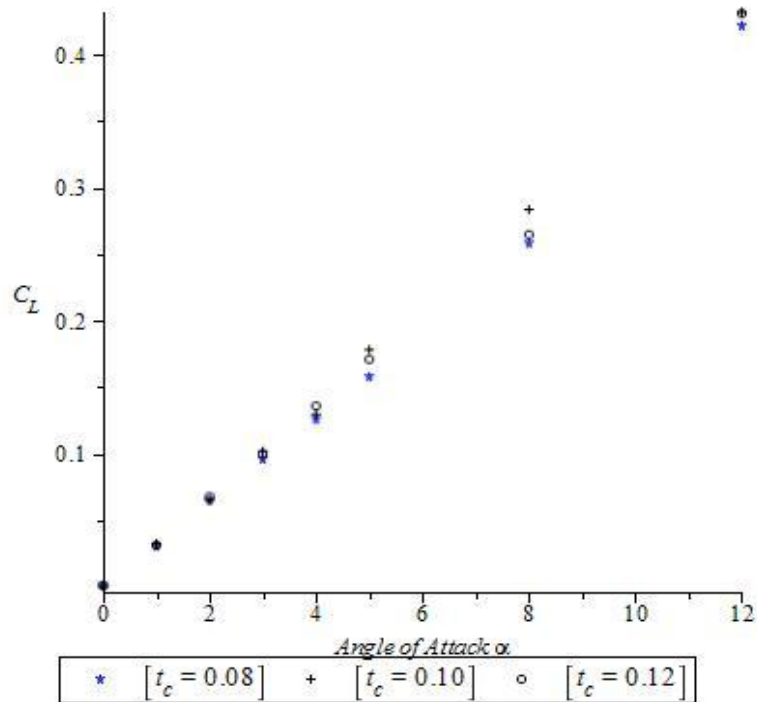
Isentropic expansion equation

$$\theta = f(M_2) - f(M_1)$$

$$f(M) = \sqrt{\frac{(\gamma + 1)}{(\gamma - 1)}} \cdot \tan^{-1} \left(\sqrt{\frac{(\gamma - 1)}{(\gamma + 1)} \cdot (M^2 - 1)} \right) - \tan^{-1}(\sqrt{M^2 - 1})$$

Results

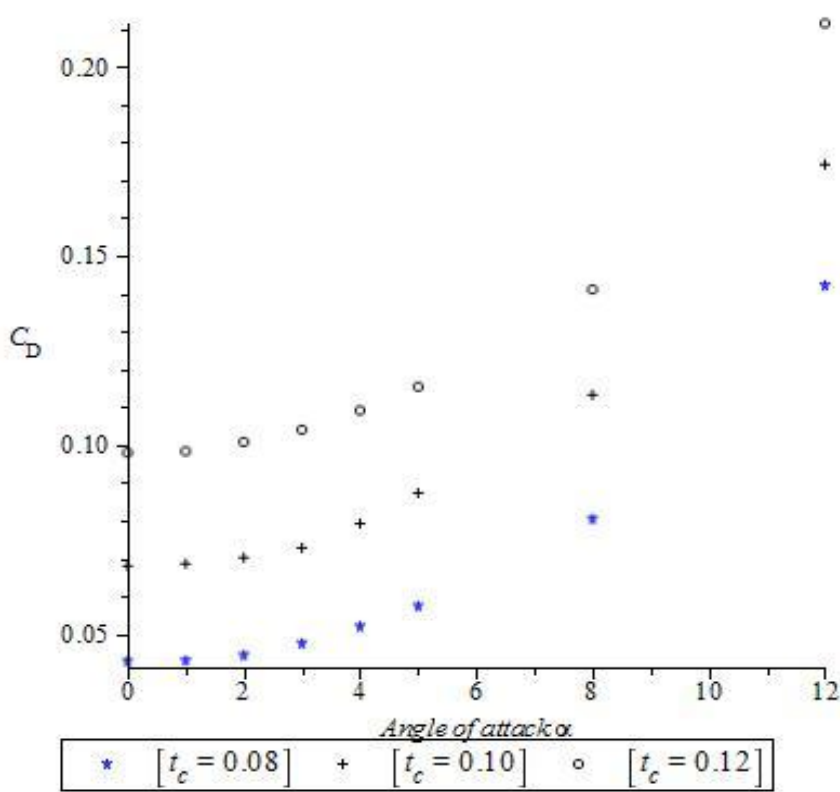
Coefficient of Lift



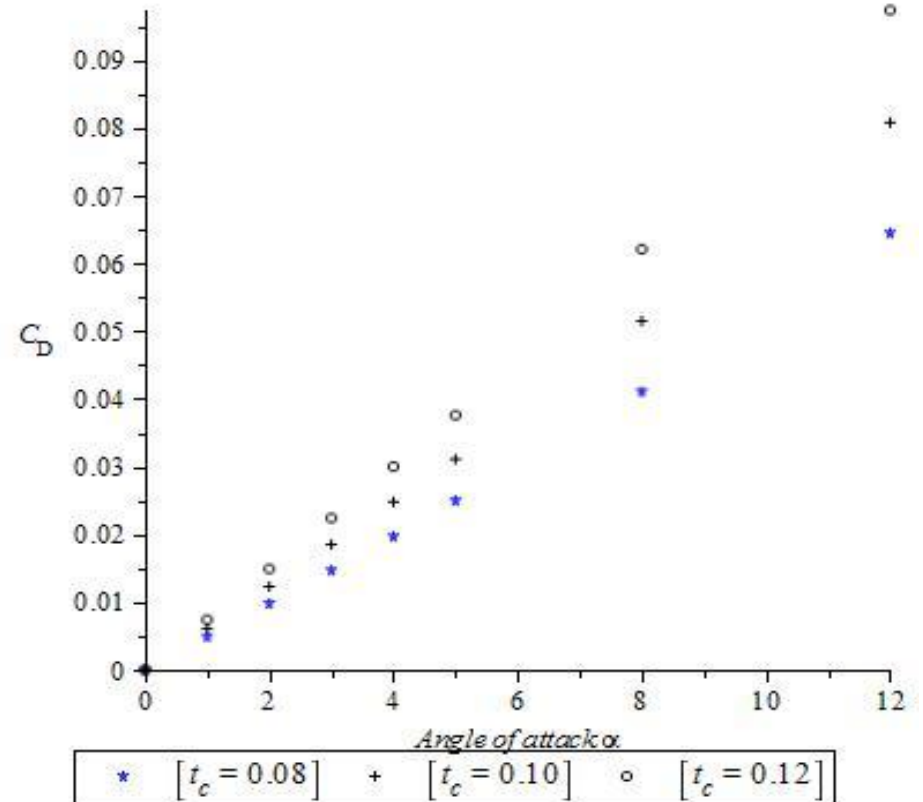
$C_L v/s \alpha$ (F.E.M Simulation)

$C_L v/s \alpha$ (SE-theory)

Coefficient of Drag



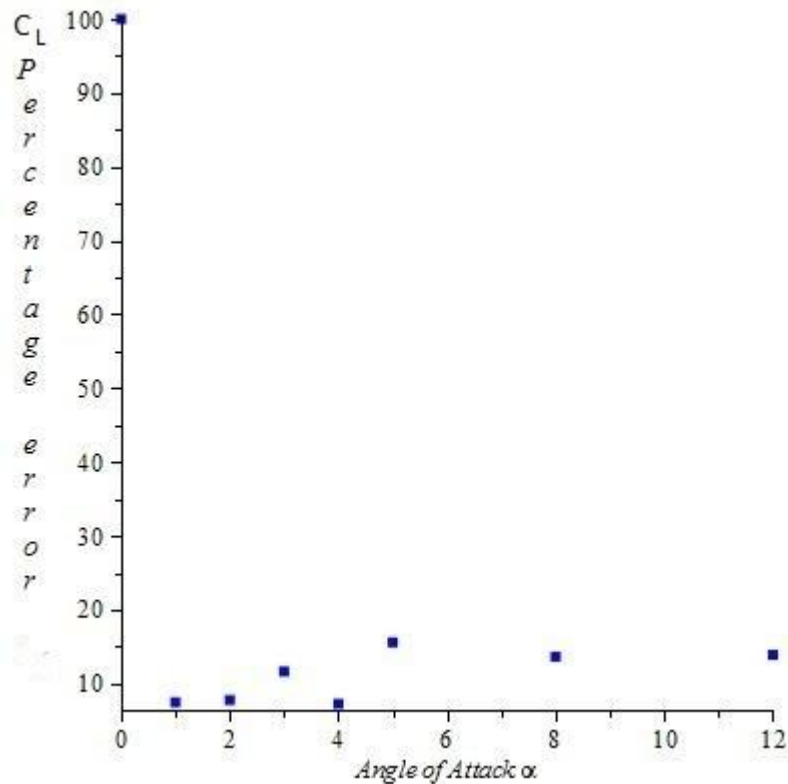
$C_D v/s \alpha$ (F.E.M Simulation)



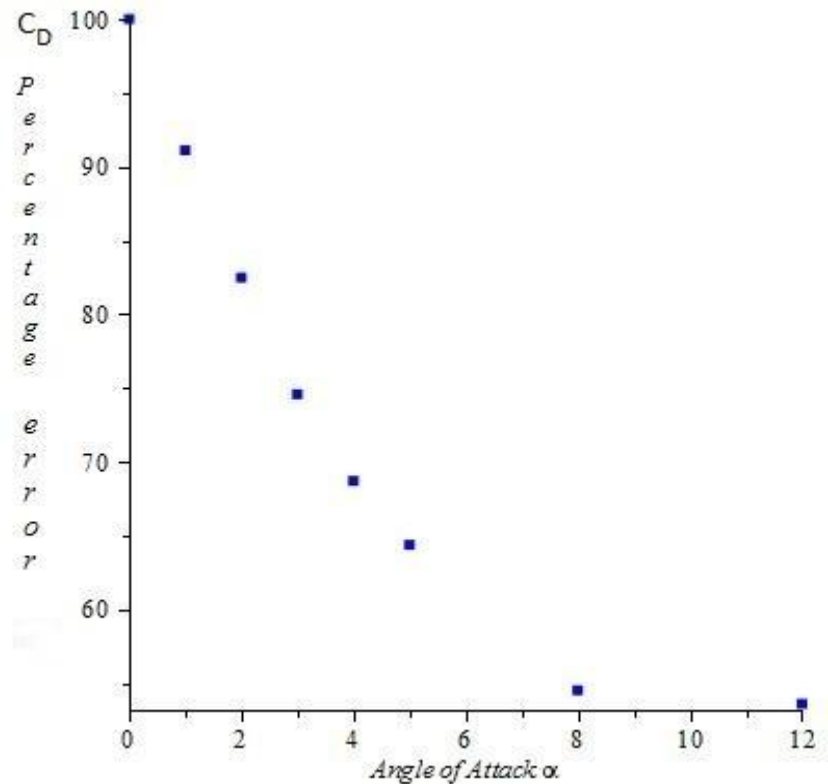
$C_D v/s \alpha$ (SE-theory)

Percentage Error estimation for ($t_c = 0.1$)

$$\frac{FEM - SE}{FEM} \times 100$$

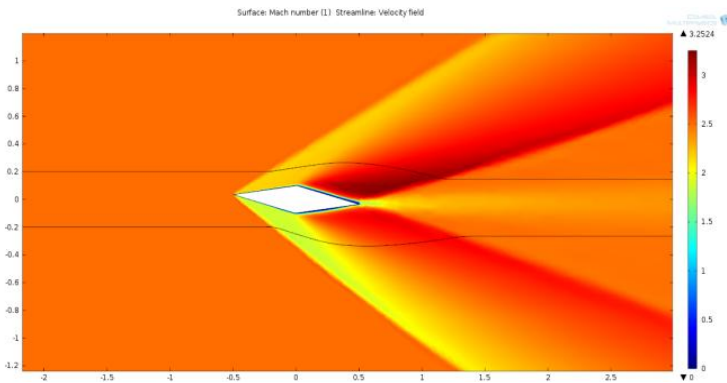


Percentage error of C_L v/s α

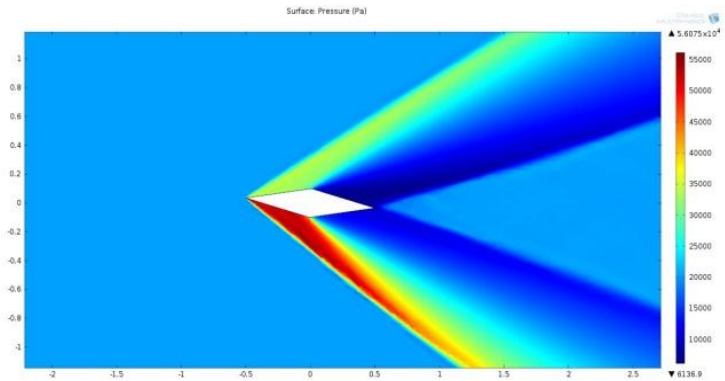


Percentage error of C_D v/s α

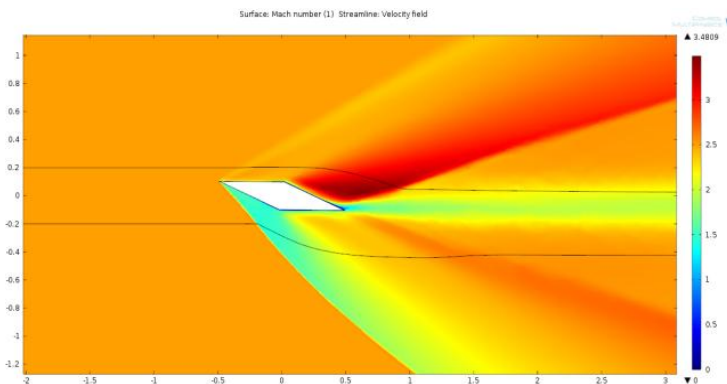
- Results for specific case ($t_c = 0.1$):



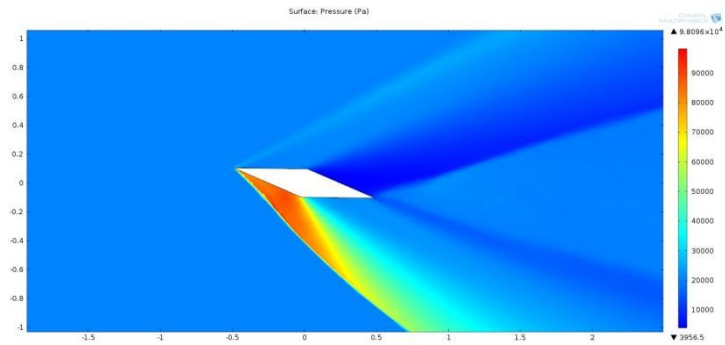
Mach number plot at $\alpha = 4$



Pressure plot at $\alpha = 4$

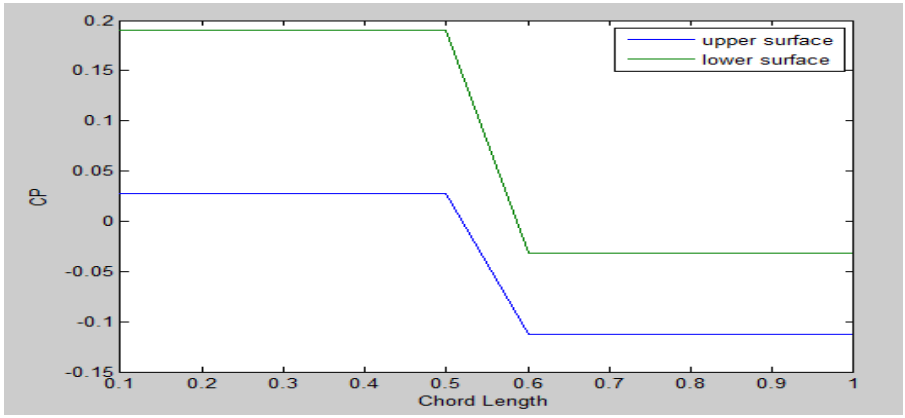


Mach number plot at $\alpha = 12$

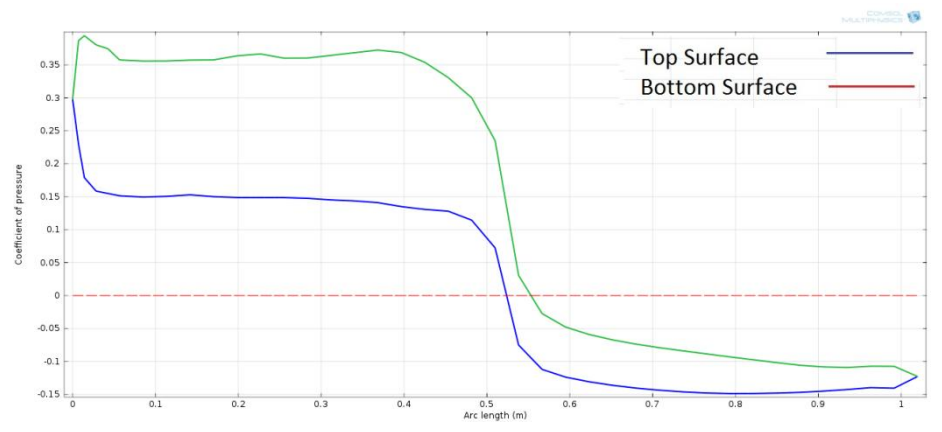


Pressure plot at $\alpha = 12$

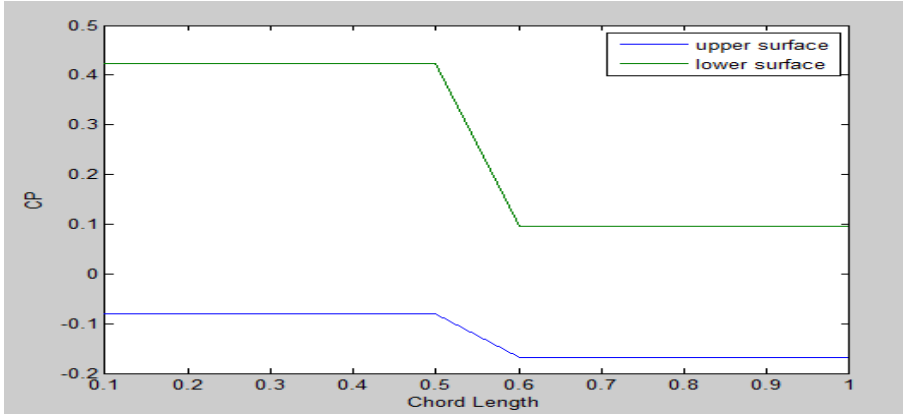
Coefficient of pressure C_p ($t_c = 0.1$)



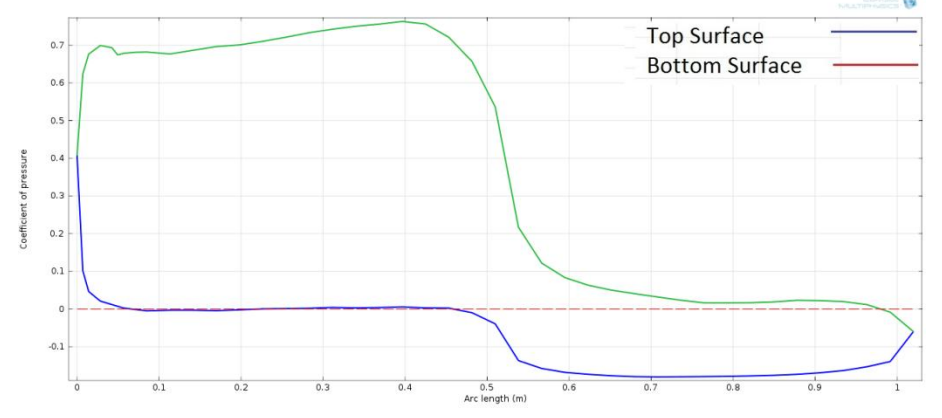
C_p (SE-theory, $\alpha = 4$)



C_p (F.E.M, $\alpha = 4$)



C_p (SE-theory, $\alpha = 12$)



C_p (F.E.M, $\alpha = 12$)

CONCLUSION

- The solutions obtained from numerical simulation performed with FEM tool is in good agreement with shock-expansion theory.
- The difference in the values of coefficients obtained from SE-theory and compressible NS numerical simulation indicates the expected viscous and wake effects.
- The values of coefficients obtained from F.E.M simulation are only applicable for infinite span wing having airfoil section congruent to aerofoil designed in this current work.

**THANK YOU
&
QUERIES ?**